

1/1

$$a) m = \frac{W}{g} = \frac{3600}{32.2} = 111.8 \text{ slugs}$$

$$b) W = 3600 \text{ lb} \left[ \frac{4.4482 \text{ N}}{\text{lb}} \right] = 16,014 \text{ N}$$

$$c) m = \frac{W}{g} = \frac{16,014}{9.81} = 1632 \text{ kg}$$

(or  $m = 111.8 \text{ slugs} \left[ \frac{14.594 \text{ kg}}{\text{slug}} \right] = 1632 \text{ kg}$ )

1/2

For a 180-lb person:

$$W = mg : 180 \text{ lb} = m(32.2 \text{ ft/sec}^2)$$

$$m = \frac{5.59 \text{ slugs}}{180 \text{ lb} \left( \frac{4.4482 \text{ N}}{\text{lb}} \right)} = 301 \text{ N}$$

$$W = mg : 301 \text{ N} = m(9.81 \text{ m/s}^2)$$

$$m = 30.6 \text{ kg}$$

1/3

$$\underline{V}_1 = 15 \left( \frac{4}{5} \underline{i} + \frac{3}{5} \underline{j} \right) = 12 \underline{i} + 9 \underline{j}$$

$$\underline{V}_2 = 12 (-\cos 60^\circ \underline{i} + \sin 60^\circ \underline{j}) = -6 \underline{i} + 10.39 \underline{j}$$

$$\underline{V}_1 + \underline{V}_2 = 15 + 12 = 27$$

$$\underline{V}_1 \cdot \underline{V}_2 = (12-6) \underline{i} + (9+10.39) \underline{j} = 6 \underline{i} + 19.39 \underline{j}$$

$$\underline{V}_1 - \underline{V}_2 = (12-6) \underline{i} + (9-10.39) \underline{j} = 6 \underline{i} - 1.39 \underline{j}$$

$$\underline{V}_1 \times \underline{V}_2 = (12 \underline{i} + 9 \underline{j}) \times (-6 \underline{i} + 10.39 \underline{j})$$

$$= (24.7 + 54) \underline{k} = 78.7 \underline{k}$$

$$\underline{V}_2 \times \underline{V}_1 = -(\underline{V}_1 \times \underline{V}_2) = -78.7 \underline{k}$$

$$\underline{V}_1 \cdot \underline{V}_2 = (12 \underline{i} + 9 \underline{j}) \cdot (-6 \underline{i} + 10.39 \underline{j})$$

$$= 12(-6) + 9(10.39) = 21.5$$

1/4

The weight of an average apple is

$$W = \frac{5 \text{ lb}}{12 \text{ apples}} = 0.417 \text{ lb}$$

Mass in slugs is  $m = \frac{W}{g} = \frac{0.417}{32.2} = 0.01294 \text{ slugs}$

Mass in kg is  $m = 0.01294 \text{ slugs} \left( \frac{14.594 \text{ kg}}{1 \text{ slug}} \right) = 0.1888 \text{ kg}$

Weight in N is  $W = mg = 0.1888(9.81) = 1.853 \text{ N}$

These apples weigh closer to 2 N each than to the rule of 1 N each!

1/5

Mass of iron sphere  $m = \rho V$

$$= (7210 \frac{\text{kg}}{\text{m}^3}) \left( \frac{4}{3} \pi (0.050 \text{ m})^3 \right) = 3.78 \text{ kg}$$

Force of mutual attraction:  $\frac{Gm^2}{d^2}$

Weight of each sphere:  $\frac{Gm_e m}{r^2}$

$$\frac{Gm^2}{d^2} = \frac{Gm_e m}{r^2}, \quad r = d \sqrt{\frac{m_e}{m}}$$

$$= 0.1 \sqrt{\frac{2(4.96 \times 10^{24})}{3.78}} \frac{1}{10^3}$$

$$= 2.251(10^3) \text{ km}$$

1/6



$r = 0.050 \text{ m}$  for all spheres

$$\underline{F}_B = \frac{Gm_1 m_2}{d_{AB}^2} = \frac{G \left( \frac{4}{3} \pi r^3 \right) \left( \frac{4}{3} \pi r^3 \right)}{d_{AB}^2}$$

$$= \frac{6.673(10^{-11}) \left[ \frac{4}{3} \pi (0.050)^3 \right]^2 (8710)(8710)}{1^2}$$

$$= 4.38(10^{-10}) \text{ N}$$

$$\underline{F}_C = \frac{Gm_1 m_2}{d_{AC}^2} = \frac{G \left[ \frac{4}{3} \pi r^3 \right]^2 \rho_1 \rho_2}{d_{AC}^2}$$

$$= \frac{6.673(10^{-11}) \left[ \frac{4}{3} \pi (0.050)^3 \right]^2 (8710)(7210)}{1^2}$$

$$= 1.175(10^{-10}) \text{ N}$$

$$\underline{R} = \underline{F}_B + \underline{F}_C = 4.38(10^{-10}) [-\sin 30^\circ \underline{i} + \cos 30^\circ \underline{j}]$$

$$+ 1.175(10^{-10}) [\sin 30^\circ \underline{i} + \cos 30^\circ \underline{j}]$$

$$\underline{R} = (3.68 \underline{i} - 12.98 \underline{j}) 10^{-10} \text{ N}$$

1/7

$$\rho = \frac{Gm_e}{(R+h)^2}$$

$$= \frac{(6.673 \times 10^{-11})(4.975 \times 10^{24})}{[(3157)(5280) + (0.50)(5280)]^2} = 2.17 \text{ kg/m}^3$$

Mass of man:  $m = \frac{W}{g} = \frac{250}{32.174} = 7.77 \text{ slugs}$

Pressure weight at  $h = 150$  miles:

$$W_h = mg_h = (7.77)(21.4) = 166.0 \text{ lb}$$

The terms "zero-g" and "weightless" are definitely misnomers in this instance.

1/8

$$mg = 0.1 mg_0$$

$$\frac{R}{(R+h)^2} g_0 = 0.1 g_0$$

Solve for  $h$  to obtain  $h = 2.16R$

# Meriam Kraige Dynamics 6th Edition Solution

**Tobias Bleicker**



## **Meriam Kraige Dynamics 6th Edition Solution:**

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*700 Solved Problems In Vector Mechanics for Engineers: Dynamics* Joseph F. Shelley, 1991-04 Suitable for 2nd year college and university engineering students, this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course. It offers the comprehensive solved problem reference in the subject. It also provides the student with the problem-solving drill.

*Essential Mechanics - Statics and Strength of Materials with MATLAB and Octave* P. Venkataraman, 2020-01-07 *Essential Mechanics: Statics and Strength of Materials with MATLAB and Octave* combines two core engineering science courses: Statics and Strength of Materials in mechanical, civil, and aerospace engineering. It weaves together various essential topics from Statics and Strength of Materials to allow discussing structural design from the very beginning. The traditional content of these courses is reordered to make it convenient to cover rigid body equilibrium and extend it to deformable body mechanics. The e-book covers the most useful topics from both courses with computational support through MATLAB and Octave. The traditional approach for engineering content is emphasized and is rigorously supported through graphics and analysis. Prior knowledge of MATLAB is not necessary. Instructions for its use in context are provided and explained. It takes advantage of the numerical, symbolic, and graphical capability of MATLAB for effective problem solving. This computational ability provides a natural procedure for what-if exploration that is important for design. The book also emphasizes graphics to understand, learn, and explore design. The idea for this book, the organization, and the flow of content is original and new. The integration of computation and the marriage of analytical and computational skills is a new, valuable experience provided by this e-book. Most importantly, the book is very interactive with respect to the code as it appears along with the analysis.

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updated second edition brings the complex mathematics of three dimensional dynamics to life with real time simulations making the equations easier to grasp Covering core topics in mechanical engineering such as kinematics dynamics vibration analysis gyroscopes gears and Euler s equations the book offers a clear and engaging approach for students professionals and enthusiasts alike With a focus on practical applications it explains everything from the laws of motion to motors and mechanisms providing a comprehensive understanding of mechanical systems New to this edition is a chapter on Power Energy and Perpetual Motion which reveals intriguing comparisons such as the energy needed to lift water versus the heat required to warm it The final chapter Rocket Science has been expanded to debunk myths about black holes and gravity humorously addressing science fiction misconceptions while proposing exciting space projects Proceedings American Society for Engineering Education. Conference,1993 **Subject Guide to Books in Print** ,1996 Philippine National Bibliography ,1988 **Mechanical Vibrations** György Szeidl,László Péter Kiss,2020-06-16 This book presents a unified introduction to the theory of mechanical vibrations The general theory of the vibrating particle is the point of departure for the field of multidegree of freedom systems Emphasis is placed in the text on the issue of continuum vibrations The presented examples are aimed at helping the readers with understanding the theory This book is of interest among others to mechanical civil and aeronautical engineers concerned with the vibratory behavior of the structures It is useful also for students from undergraduate to postgraduate level The book is based on the teaching experience of the authors

*Proceedings of the AIAA Modeling and Simulation Technologies Conference* American Institute of Aeronautics and Astronautics,1997 Topics for the 1997 conference on modelling and simulation technologies included motion systems rotor craft and air cushion vehicle dynamics and modelling pilot training and low cost simulation weapons and engagement modelling and simulation simulator network and information technologies visual radarf and environmental modelling and simulation test and evaluation space systems simulator fidelity aircraft dynamics modelling and performance simulator development and software re use human factors and research and test facilities Annual Conference Proceedings American Society for Engineering Education. Conference,1993 **Solving Dynamics Problems in Mathcad by Brian Harper t/a Engineering Mechanics Dynamics 6th Edition by Meriam and Kraige** J. L. Meriam,L. G. Kraige,2006-12-15 *Forthcoming Books* Rose Arny,1992

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