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1. An object is launched horizontally from a cliff. The cliff is 80m high and the object has an initial velocity of 50m/s. Find:

A. The initial x velocity

$$v_{xi} = 50 \text{ m/s}$$

B. The initial y velocity

$$v_{yi} = 0$$

C. The final x velocity

$$v_{fx} = 50 \text{ m/s}$$

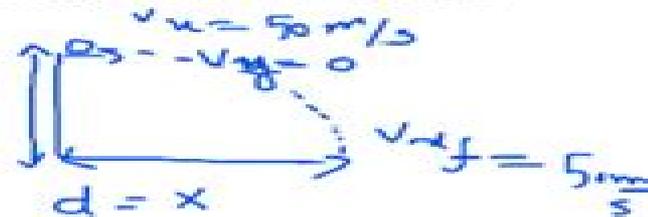
D. The final y velocity

$$v_{fy} = 0$$

$$a = -10 \text{ m/s}^2$$

$$v_{fy}^2 = v_{iy}^2 + 2ad$$

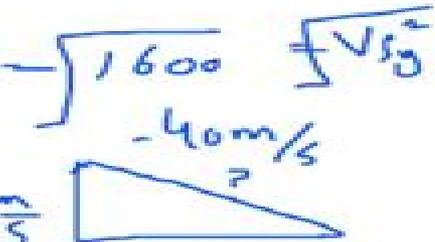
$$v_{fy}^2 = 0 + 2(10)(-80)$$



E. The final resultant velocity

$$c^2 = a^2 + b^2$$

$$\sqrt{c^2} = \sqrt{50^2 + (-40 \text{ m/s})^2} = \boxed{64 \frac{\text{m}}{\text{s}} = V}$$



F. The angle at which the projectile strikes the ground

$$\tan \theta = \frac{v_y}{v_x} \Rightarrow \theta = \tan^{-1} \frac{v_y}{v_x} = \tan^{-1} \frac{40}{50} = 38.65^\circ$$

G. How far from the base of the cliff the projectile lands

$$v_x = \frac{d}{t} = d = v_x t \quad t = \sqrt{\frac{2 \cdot 80}{10}} = \sqrt{16} = 4 \text{ sec}$$

$$d = 50 \times 4 \text{ sec} = 200 \text{ m}$$



2. A projectile is launched at a velocity of 100m/s at a 30 degree angle. Find:

A. The initial x velocity

$$v_x = v \cos \theta$$

$$= 100 \cos 30 = 86.6 \frac{\text{m}}{\text{s}}$$



B. The initial y velocity

$$\sin \theta = \frac{p}{h} = \frac{v_y}{v}$$

$$v_y = v \sin \theta$$

$$100 \sin 30 = 50 \text{ m/s}$$

$$\cos \theta = \frac{\text{Base}}{\text{hyp}}$$

$$\cos 30 = \frac{v_x}{v} = v_x = v \cos \theta$$

$$s = v_i t + \frac{1}{2} a t^2$$

$$d = 0 + \frac{1}{2} a t^2$$

$$\sqrt{\frac{2d}{a}} = \sqrt{\frac{2v^2}{a}}$$

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DJ Losen



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Proceedings of the National Conference on Advanced Manufacturing & Robotics, January 10-11, 2004 S. N. Shome, Jhankar Basu, G. P. Sinha, 2004 Contributed papers presented at the conference held at Central Mechanical Engineering Research Institute Durgapur Applied Mechanics Reviews, 1995 **Introduction to Biological Physics for the Health and Life Sciences** Kirsten Franklin, Paul Muir, Terry Scott, Lara Wilcocks, Paul Yates, 2010-08-13 This book aims to demystify fundamental biophysics for students in the health and biosciences required to study physics and to understand the mechanistic behaviour of biosystems The text is well supplemented by worked conceptual examples that will constitute the main source for the students while combining conceptual examples and practice problems with more quantitative examples and recent technological advances The Physics Teacher, 1970 *Robot Modeling and Kinematics* Rachid Manseur, 2006 Robot Modeling and Kinematics teaches the fundamental topics of robotics using cutting edge visualization software and computer tools to illustrate topics and provide a comprehensive process of teaching and learning The book provides an introduction to robotics with an emphasis on the study of robotic arms their mathematical description and the equations describing their motion It teaches how to model robotic arms efficiently and analyze their kinematics The kinematics of robot manipulators is also presented beginning with the use of simple robot mechanisms and progressing to the most complex robot manipulator structures While mathematically rigorous the book's focus is on ease of understanding of the concepts with interactive animated computer graphics illustrations and modeling software that allow clear understanding of the material covered in the book All necessary computations are concisely explained and software is provided that greatly eases the computational burden normally associated with robotics Written for use in a robotics course or as a professional reference Robot Modeling and Kinematics is an essential resource that provides a thorough understanding of the topics of modeling and kinematics Scientific and Technical Aerospace Reports, 1981 Felder's Comprehensive, 2005 Edition Nick Felder, 2005-07-14 Every industry has its standard professional directory advertising has its Black Book manufacturing its Thomas's Register except that is for architecture and design and construction While there are dozens of smaller directories each addressing a specific market niche none speak to all three industries in a comprehensive way And larger product directories like Sweets are advertising driven and therefore incomplete Felder's Comprehensive is the first pan industry guide of its kind and it is many times more comprehensive than the nearest competitor It is an annual desk reference directory and product source guide with more reference information than any other title currently available It contains thousands of listings of time sensitive and timeless reference information for anyone involved in the business or practice of architecture design design build construction interior design facility management and real estate development For example readers can find listings for more than 12 000 manufacturers of furnishings fixtures equipment and materials listed alphabetically and most importantly by product category Felder's also lists design competitions domestic and

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