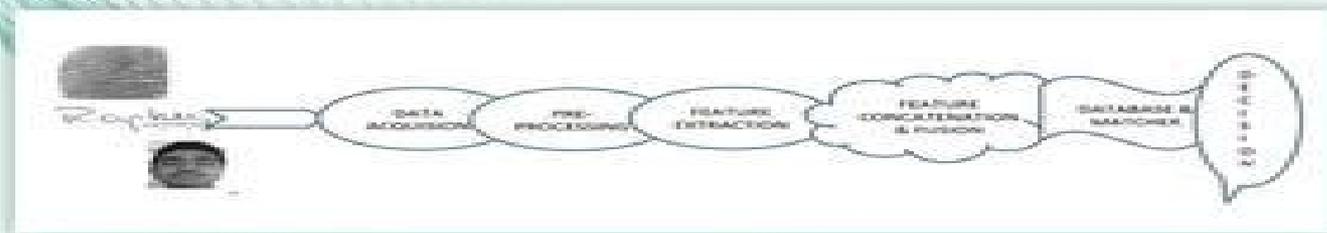


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SUDESH K. KASHYAP AND AILNENI SANKETH**



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Mathematical Modelling of Aerospace Dynamic Systems with Practical Applications Jitendra R. Raol, V.P.S. Naidu, 2025-03-18 Mathematical Modelling of Aerospace Dynamic Systems with Practical Applications provides mathematical models for several aerospace dynamic systems aircraft rotorcraft missiles unmanned aerial vehicles UAVs mini air vehicles MAVs autonomous underwater vehicles AUWVs and satellite coordinate systems Presenting the use of mathematical models for analysis prediction and control of these systems this book discusses numerous applications in aircraft helicopter parameter estimation guidance and navigation of these vehicles underwater object search aerial terrain mapping and satellite orbit determination It explains path planning with obstacle avoidance object occlusion detection and tracking and multisensory target tracking and sensor data fusion This book is intended for senior undergraduate mechanical and aerospace engineering students taking courses in aerospace systems and dynamics flight dynamics and control and dynamical systems and estimation Instructors will be able to utilize a Solutions Manual and Figure Slides for their course

Situation Assessment in Aviation Jitendra R. Raol, Sudesh K. Kashyap, Lakshmi Shrinivasan, 2024-02-29 Situation Assessment in Aviation focuses on new aspects of soft computing technologies for the evaluation and assessment of situations in aviation scenarios It considers technologies emerging from multisensory data fusion MSDF Bayesian networks BN and fuzzy logic FL to assist pilots in their decision making Studying MSDF BN and FL from the perspective of their applications to the problem of situation assessment the book discusses the development of certain soft technologies that can be further used for devising more sophisticated technologies for a pilot s decision making

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Advances in Computer Vision Kohei Arai,Supriya Kapoor,2019-04-23 This book presents a remarkable collection of chapters covering a wide range of topics in the areas of Computer Vision both from theoretical and application perspectives It gathers the proceedings of the Computer Vision Conference CVC 2019 held in Las Vegas USA from May 2 to 3 2019 The conference attracted a total of 371 submissions from pioneering researchers scientists industrial engineers and students all around the world These submissions underwent a double blind peer review process after which 118 including 7 poster papers were selected for inclusion in these proceedings The book s goal is to reflect the intellectual breadth and depth of current research on computer vision from classical to intelligent scope Accordingly its respective chapters address state of the art intelligent methods and techniques for solving real world problems while also outlining future research directions Topic areas covered include Machine Vision and Learning Data Science Image Processing Deep Learning and Computer Vision Applications

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Nonlinear Filtering Jitendra R. Raol,Girija Gopalratnam,Bhekisipho Twala,2017-07-12 Nonlinear Filtering covers linear and nonlinear filtering in a comprehensive manner with appropriate theoretic and practical development Aspects of modeling estimation recursive

filtering linear filtering and nonlinear filtering are presented with appropriate and sufficient mathematics A modeling control system approach is used when applicable and detailed practical applications are presented to elucidate the analysis and filtering concepts MATLAB routines are included and examples from a wide range of engineering applications including aerospace automated manufacturing robotics and advanced control systems are referenced throughout the text

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