

Dynamics of a Quadcopter

- Adjacent rotors of a quadcopter must rotate in opposite direction.
- Diagonally opposite rotors must rotate in the same direction, to provide yaw stability.
- Pitch or yaw can be achieved by varying the rotor speeds, i.e., by increasing speeds of two rotors while decreasing speeds of the other two.
- Once the pitch is altered, the lift vector tilts away from the vertical, causing a translational motion.



Quadcopter Dynamics Simulation And Control Introduction

Brent Komer



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