

Module 5: Hydraulic Systems

Lecture 1

Introduction

1. Introduction

The controlled movement of parts or a controlled application of force is a common requirement in the industries. These operations are performed mainly by using electrical machines or diesel, petrol and steam engines as a prime mover. These prime movers can provide various movements to the objects by using some mechanical attachments like screw jack, lever, rack and pinions etc. However, these are not the only prime movers. The enclosed fluids (liquids and gases) can also be used as prime movers to provide controlled motion and force to the objects or substances. The specially designed enclosed fluid systems can provide both linear as well as rotary motion. The high magnitude controlled force can also be applied by using these systems. This kind of enclosed fluid based systems using pressurized incompressible liquids as transmission media are called as hydraulic systems. The hydraulic system works on the principle of Pascal's law which says that the pressure in an enclosed fluid is uniform in all the directions. The Pascal's law is illustrated in figure 5.1.1. The force given by fluid is given by the multiplication of pressure and area of cross section. As the pressure is same in all the direction, the smaller piston feels a smaller force and a large piston feels a large force. Therefore, a large force can be generated with smaller force input by using hydraulic systems.

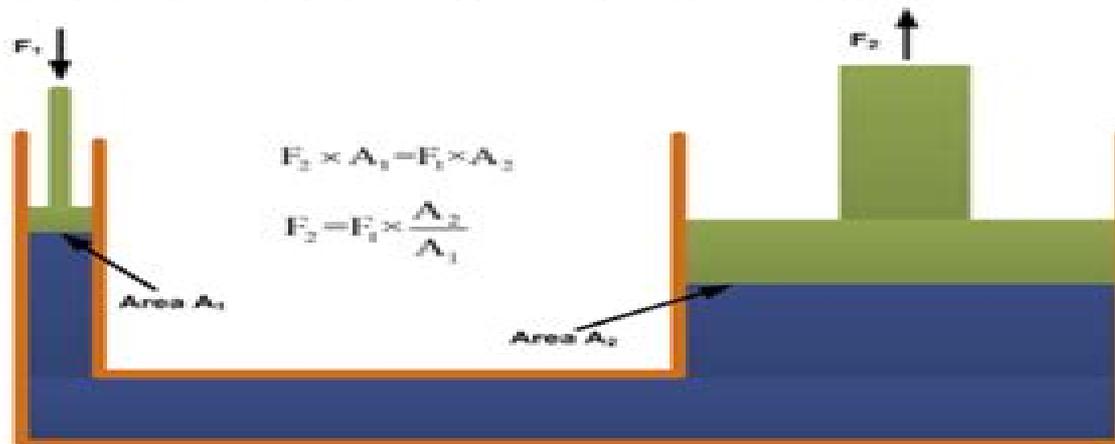


Figure 5.1.1 Principle of hydraulic system

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Michael Brown



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Bhattacharyya, Saket Verma, A. R. Harikrishnan, 2023-04-17 This book presents the select proceedings of the 48th National Conference on Fluid Mechanics and Fluid Power FMFP 2021 held at BITS Pilani in December 2021 It covers the topics such as fluid mechanics measurement techniques in fluid flows computational fluid dynamics instability transition and turbulence fluid structure interaction multiphase flows micro and nanoscale transport bio fluid mechanics aerodynamics turbomachinery propulsion and power The book will be useful for researchers and professionals interested in the broad field of mechanics

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American Council on Education, 2000 *Scientific and Technical Aerospace Reports*, 1979 Control of Variable-Geometry

Vehicle Suspensions Balázs Németh, Péter Gáspár, 2023-07-08 This book provides a thorough and fresh treatment of the control of innovative variable geometry vehicle suspension systems A deep survey on the topic which covers the varying types of existing variable geometry suspension solutions introduces the study The book discusses three important aspects of the subject robust control design nonlinear system analysis and integration of learning and control methods The importance of variable geometry suspensions and the effectiveness of design methods implemented in the autonomous functionalities of electric vehicles functionalities like independent steering and torque vectoring are illustrated The authors detail the theoretical background of modeling control design and analysis for each functionality The theoretical results achieved through simulation examples and hardware in the loop scenarios are confirmed The book highlights emerging ideas of applying machine learning based methods in the control system with guarantees on safety performance The authors propose

novel control methods based on the theory of robust linear parameter varying systems with examples for various suspension systems Academic researchers interested in automotive systems and their counterparts involved in industrial research and development will find much to interest them in the eleven chapters of Control of Variable Geometry Vehicle Suspensions

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