

1. A robot with means to understand its environment and the ability to successfully complete a task despite changes in the surroundings is called
 - a. Intelligent robot
 - b. Numerical control robot
 - c. Freely programmable robot
 - d. SCARA robot

Ans: A

2. The main function of _____ module is to take signals from field devices, modify, isolate and send to PLCs CPU.
 - a. stepper motor
 - b. communication
 - c. output
 - d. input

Ans: D

3. _____ language is used commonly for programming the PLC
 - a. Ladder diagram
 - b. English
 - c. Assembly level
 - d. Machine

Mechatronics Question Answers

Marco Casella



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