Giuseppe Conte · Claude H. Moog
Anna Maria Perdon

Algebraic Methods for Nonlinear Control Systems

Theory and Applications

2nd Edition

Springer

Algebraic Methods For Nonlinear Control Systems Communications And Control Engineering

M. Fliess,Michiel Hazewinkel

Algebraic Methods For Nonlinear Control Systems Communications And Control Engineering:
  Algebraic Methods for Nonlinear Control Systems Giuseppe Conte,Claude H. Moog,Anna Maria Perdon,2007
  Algebraic Methods for Nonlinear Control Systems Giuseppe Conte,Claude H. Moog,Anna Maria Perdon,2007-01-19
A self contained introduction to algebraic control for nonlinear systems suitable for researchers and graduate students Algebraic Methods for Nonlinear Control Systems develops a linear algebraic alternative to the usual differential geometric approach to nonlinear control using vector spaces over suitable fields of nonlinear functions It describes a range of results some of which can be derived using differential geometry but many of which cannot They include classical and generalized realization in the nonlinear context accessibility and observability recast for the linear algebraic setting discussion and solution of basic feedback problems results for dynamic and static state and output feedback Dynamic feedback and realization are shown to be dealt with and solved much more easily in the algebraic framework The second edition has been completely revised with new text examples and exercises it is divided into two parts necessary methodology and applications to control problems   *Nonlinear Control Systems* Alberto Isidori,2013-04-17 The purpose of this book is to present a self contained description of the fun damentals of the theory of nonlinear control systems with special emphasis on the differential geometric approach The book is intended as a graduate text as weil as a reference to scientists and engineers involved in the analysis and design of feedback systems The first version of this book was written in 1983 while I was teach ing at the Department of Systems Science and Mathematics at Washington University in St Louis This new edition integrates my subsequent teaching experience gained at the University of Illinois in Urbana Champaign in 1987 at the Carl Cranz Gesellschaft in Oberpfaffenhofen in 1987 at the University of California in Berkeley in 1988 In addition to a major rearrangement of the last two Chapters of the first version this new edition incorporates two additional Chapters at a more elementary level and an exposition of some relevant research findings which have occurred since 1985   **Nonlinear Control Systems II** Alberto Isidori,2012-12-06 The purpose of this book is to present a self contained and coordinated de scription of several design methods for nonlinear control systems with special emphasis on the problem of achieving stability globally or on arbitrarily large domains in the presence of model uncertainties The book is intended to be a continuation of my earlier book Nonlinear Control Systems dealing with the fundamentals of the theory of nonlinear control systems whose third edition was published in 1995 In this respect it is written in the form of a second volume of a single work and uses a numbering system that continues the one adopted in the earlier book with which the overlap is essentially insignificant The book is intended as a graduate text as well as a reference to scientists and engineers interested in the design of feedback laws for nonlinear control systems In the last decade methods for global stabilization of nonlinear systems have experienced a vigorous growth   *Nonlinear Control Systems* G. Conte,C.H. Moog,A.M. Perdon,2014-03-12 This book provides a unique and alternative approach to the study of nonlinear control systems with applications The approach presented is based on the

use of algebraic methods which are intrinsically linear rather than differential geometric methods which are more commonly found in other reference works on the subject This allows the exposition to remain simple from a mathematical point of view and accessible for everyone who has a good understanding of linear control theory The book is divided into the following three parts Part 1 is devoted to mathematical preliminaries and to the development of tools and methods for system analysis Part 2 is concerned with solving specific control problems including disturbance decoupling non interactive control model matching and feedback linearization problems Part 3 introduces differential algebraic notions and discusses their applications to nonlinear control and system theory With numerous examples used to illustrate theoretical results this self contained and comprehensive volume will be of interest to all those who have a good basic knowledge of standard linear control systems **Observer Design for Nonlinear Dynamical Systems** Driss Boutat,Gang Zheng,2021-07-02 This book presents a differential geometric method for designing nonlinear observers for multiple types of nonlinear systems including single and multiple outputs fully and partially observable systems and regular and singular dynamical systems It is an exposition of achievements in nonlinear observer normal forms The book begins by discussing linear systems introducing the concept of observability and observer design and then explains the difficulty of those problems for nonlinear systems After providing foundational information on the differential geometric method the text shows how to use the method to address observer design problems It presents methods for a variety of systems The authors employ worked examples to illustrate the ideas presented Observer Design for Nonlinear Dynamical Systems will be of interest to researchers graduate students and industrial professionals working with control of mechanical and dynamical systems **Algebraic and Geometric Methods in Nonlinear Control Theory** M. Fliess,Michiel Hazewinkel,2012-12-06 Approach your problems from the right end It isn t that they can t see the solution It is and begin with the answers Then one day that they can t see the problem perhaps you will find the final question G K Chesterton The Scandal of Father The Hermit Clad in Crane Feathers in R Brown The pointof a Pin van GuIik s The Chinese Maze Murders Growing specialization and diversification have brought a host of monographs and textbooks on increasingly specialized topics However the tree of knowledge of mathematics and related fields does not grow only by putting forth new branches It also happens quite often in fact that branches which were thought to be completely disparate are suddenly seen to be related Further the kind and level of sophistication of mathematics applied in various sciences has changed drastically in recent years measure theory is used non trivially in regional and theoretical economics algebraic geometry interacts with physics ihe Minkowsky lemma coding theory and the structure of water meet one another in packing and covering theory quantum fields crystal defects and mathematical programming profit from homotopy theory Lie algebras are relevant to filtering and prediction and electrical engineering can use Stein spaces And in addition to this there are such new emerging subdisciplines as experimental mathematics CFD completely integrable systems chaos synergetics and large scale order which are almost impossible to fit into the existing classification schemes They draw

upon widely different sections of mathematics   <u>Linearization of Nonlinear Control Systems</u> Hong-Gi Lee,2022-09-02 This textbook helps graduate level student to understand easily the linearization of nonlinear control system Differential geometry is essential to understand the linearization problems of the control nonlinear systems In this book the basics of differential geometry needed in linearization are explained on the Euclidean space instead of the manifold for students who are not accustomed to differential geometry Many Lie algebra formulas used often in linearization are also provided with proof The conditions in the linearization problems are complicated to check because the Lie bracket calculation of vector fields by hand needs much concentration and time This book provides MATLAB programs for most of the theorems The book also includes end of chapter problems and other pedagogical aids to help understanding and self study   *Mathematical Reviews* ,2007

Proceedings, IEEE Control Systems Society ... Symposium on Computer-Aided Control System Design (CACSD). ,2004   **Advanced Control Methods for Industrial Processes** Pablo A. López-Pérez,Omar Jacobo Santos Sánchez,Liliam Rodríguez Guerrero,Patricio Ordaz,2025-03-20 A detailed introduction to mathematical models for new and established control engineers Control engineering is a system that helps us understand electrical physical chemical and biochemical systems through the use of mathematical modeling using inputs outputs and simulations These experimental platforms are implemented in most systems of modern advanced control engineering Advanced Control Methods for Industrial Processes provides a solid grounding in traditional control techniques It emphasizes practical application methods alongside the underlying theory and core instrumentation Each chapter discusses the full profile of the technology covered from the field layer and control layer to its implementation It also includes the interfaces for advanced control systems between controllers and systems theory between different layers and between operators systems Through an emphasis on the practical issues of components devices and hardware circuits the book offers working principles and operation mechanisms that allow an engineer to put theory into practice for the advanced control techniques Advanced Control Methods for Industrial Processes readers will also find A practical overview on advanced control methods applied to real time and in silico systems Specific parameters install procedures calibration and configuration methodologies necessary to conduct the relevant models Clear insights into the necessary mathematical models Tutorial material to facilitate the understanding of core concepts Advanced Control Methods for Industrial Processes is an ideal companion for process engineers control engineers and chemists in industry   **OAR** ,1967   *Analysis and Optimization of Systems* Alain Bensoussan,Jacques-Louis Lions,1990   *Algebraic and Differential Methods for Nonlinear Control Theory* Rafael Martínez-Guerra,Oscar Martínez-Fuentes,Juan Javier Montesinos-García,2019-01-30 This book is a short primer in engineering mathematics with a view on applications in nonlinear control theory In particular it introduces some elementary concepts of commutative algebra and algebraic geometry which offer a set of tools quite different from the traditional approaches to the subject matter This text begins with the study of elementary set and map theory Chapters 2 and 3 on

group theory and rings respectively are included because of their important relation to linear algebra the group of invertible linear maps or matrices and the ring of linear maps of a vector space Homomorphisms and Ideals are dealt with as well at this stage Chapter 4 is devoted to the theory of matrices and systems of linear equations Chapter 5 gives some information on permutations determinants and the inverse of a matrix Chapter 6 tackles vector spaces over a field Chapter 7 treats linear maps resp linear transformations and in addition the application in linear control theory of some abstract theorems such as the concept of a kernel the image and dimension of vector spaces are illustrated Chapter 8 considers the diagonalization of a matrix and their canonical forms Chapter 9 provides a brief introduction to elementary methods for solving differential equations and finally in Chapter 10 nonlinear control theory is introduced from the point of view of differential algebra

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